

## Ďalšie vzťahy pre študentov MAN3c

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$$

$$\sin^2 \theta = \frac{1 - \cos(2\theta)}{2}$$

$$2 \cos \theta \cos \varphi = \cos(\theta - \varphi) + \cos(\theta + \varphi)$$

$$2 \sin \theta \cos \varphi = \sin(\theta + \varphi) + \sin(\theta - \varphi)$$

$$\sin(2\theta) = 2 \cos \theta \sin \theta = \frac{2 \tan \theta}{1 + \tan^2 \theta}$$

$$\sin(n\theta) = \sum_{k \text{ nep.}} (-1)^{(k-1)/2} \binom{n}{k} \cos^{n-k} \theta \sin^k \theta$$

$$\frac{\pi}{2} = \arcsin x + \arccos x$$

$$\cosh^2 x - \sinh^2 x = 1$$

$$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$$

$$\cos^2 \theta = \frac{1 + \cos(2\theta)}{2}$$

$$2 \sin \theta \sin \varphi = \cos(\theta - \varphi) - \cos(\theta + \varphi)$$

$$2 \cos \theta \sin \varphi = \sin(\theta + \varphi) - \sin(\theta - \varphi)$$

$$\cos(2\theta) = \cos^2 \theta - \sin^2 \theta = \frac{1 - \tan^2 \theta}{1 + \tan^2 \theta}$$

$$\cos(n\theta) = \sum_{k \text{ pár.}} (-1)^{k/2} \binom{n}{k} \cos^{n-k} \theta \sin^k \theta$$

$$\frac{\pi}{2} = \arctan x + \operatorname{arccot} x$$

Pre parametricky danú  $C^2$  krivku  $\mathbf{r} : [a, b] \rightarrow \mathbb{R}^3$  ( $\mathbf{r}' \neq 0$ ) je **krivosť**  $\kappa(t) = \frac{\|\mathbf{r}' \times \mathbf{r}''\|}{\|\mathbf{r}'\|^3}$  a ak je  $C^3$ , potom jej **torzia** v neinflexnom bode je  $\tau = \frac{(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}'''}{\|\mathbf{r}' \times \mathbf{r}''\|^2}$ .

**Frenetove-Serretove vzorce:**

$$\frac{d}{dt} \begin{bmatrix} \mathbf{u} \\ \mathbf{a}_n \\ \mathbf{b} \end{bmatrix} = \|\mathbf{r}'\| \begin{bmatrix} 0 & \kappa & 0 \\ -\kappa & 0 & \tau \\ 0 & -\tau & 0 \end{bmatrix} \begin{bmatrix} \mathbf{u} \\ \mathbf{a}_n \\ \mathbf{b} \end{bmatrix}$$

**Sférické súradnice v  $\mathbb{R}^3$ :**

$$x = \rho \sin \phi \cos \theta, \quad \rho = \sqrt{x^2 + y^2 + z^2},$$

$$y = \rho \sin \phi \sin \theta, \quad \phi = \arccos \frac{z}{\rho} = \arctan \frac{\sqrt{x^2 + y^2}}{z}$$

$$z = \rho \cos \phi, \quad \theta = \arctan \left( \frac{y}{x} \right), \quad x > 0 \quad [-\pi/2 < \theta \leq \pi/2]$$

kde  $-\pi < \theta \leq \pi$ ,  $0 < \phi < \pi$ ,  $\rho > 0$  a  $h_\rho = 1$ ,  $h_\phi = \rho$ ,  $h_\theta = \rho \sin \phi$ .

**Sférické súradnice v  $\mathbb{R}^n$ :**

$$x_1 = \rho \cos \phi_1,$$

⋮

$$x_j = \rho \cos \phi_j \prod_{i=1}^{j-1} \sin \phi_i,$$

⋮

$$x_n = \rho \prod_{i=1}^{n-1} \sin \phi_i$$

$\rho > 0$ ,  $\phi_{n-1} \in (-\pi, \pi]$ ,  $\phi_i \in (0, \pi)$ ,  $i = 1, \dots, n-2$  a  $h_\rho = \rho$ ,  $h_{\phi_i} = \rho \prod_{i=1}^{j-1} \sin \phi_i$

Nech  $\phi, \mathbf{F} \in C^1$ , potom pre (krivočiarié) ortogonálne súradnice platí

•

$$\nabla\phi = \left( \frac{1}{h_1} \frac{\partial\phi}{\partial q_1}, \frac{1}{h_2} \frac{\partial\phi}{\partial q_2}, \frac{1}{h_3} \frac{\partial\phi}{\partial q_3} \right)$$

•

$$\operatorname{div} \mathbf{F} = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} (F_1 h_2 h_3) + \frac{\partial}{\partial q_2} (F_2 h_1 h_3) + \frac{\partial}{\partial q_3} (F_3 h_2 h_1) \right]$$

•

$$\operatorname{rot} \mathbf{F} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} \mathbf{h}_1 & \mathbf{h}_2 & \mathbf{h}_3 \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q_3} \\ F_1 h_1 & F_2 h_2 & F_3 h_3 \end{vmatrix}$$

•

$$\Delta\phi = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} \left( \frac{h_2 h_3}{h_1} \frac{\partial\phi}{\partial q_1} \right) + \frac{\partial}{\partial q_2} \left( \frac{h_1 h_3}{h_2} \frac{\partial\phi}{\partial q_2} \right) + \frac{\partial}{\partial q_3} \left( \frac{h_2 h_1}{h_3} \frac{\partial\phi}{\partial q_3} \right) \right]$$

Vlastnosti skalárneho a vektorového súčinu: Vzťahy diferenciálnych operátorov

•  $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$

•  $\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$

•  $\mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}$

•  $(\mathbf{A} + \mathbf{B}) \cdot \mathbf{C} = \mathbf{A} \cdot \mathbf{C} + \mathbf{B} \cdot \mathbf{C}$

•  $(\mathbf{A} + \mathbf{B}) \times \mathbf{C} = \mathbf{A} \times \mathbf{C} + \mathbf{B} \times \mathbf{C}$

•  $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})$

•  $\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = (\mathbf{A} \cdot \mathbf{C}) \mathbf{B} - (\mathbf{A} \cdot \mathbf{B}) \mathbf{C}$

•  $(\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{C})(\mathbf{B} \cdot \mathbf{D}) - (\mathbf{B} \cdot \mathbf{C})(\mathbf{A} \cdot \mathbf{D})$

•  $(\mathbf{A} \times \mathbf{B}) \times (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{B} \times \mathbf{D}) \mathbf{C} - (\mathbf{A} \cdot \mathbf{B} \times \mathbf{C}) \mathbf{D}$

•  $\operatorname{div} \phi \mathbf{u} = \phi \operatorname{div} \mathbf{u} + \nabla\phi \cdot \mathbf{u}$

•  $\operatorname{div} (\mathbf{u} \times \mathbf{v}) = \operatorname{rot} \mathbf{u} \cdot \mathbf{v} - \operatorname{rot} \mathbf{v} \cdot \mathbf{u}$

•  $\operatorname{rot} (\mathbf{u} \times \mathbf{v}) = (\mathbf{v} \cdot \nabla) \mathbf{u} - (\mathbf{u} \cdot \nabla) \mathbf{v} + (\operatorname{div} \mathbf{v}) \mathbf{u} - (\operatorname{div} \mathbf{u}) \mathbf{v}$

•  $\operatorname{rot} (\phi \mathbf{u}) = \phi \operatorname{rot} \mathbf{u} + \nabla\phi \times \mathbf{u}$

•  $\operatorname{rot} \nabla\phi = \mathbf{0}$

•  $\operatorname{rot} (\operatorname{rot} \mathbf{u}) = \nabla(\operatorname{div} \mathbf{u}) - \Delta\mathbf{u}$

•  $\operatorname{div} (\operatorname{rot} \mathbf{u}) = 0$

•  $\nabla(\mathbf{u} \cdot \mathbf{v}) = \mathbf{u} \times \operatorname{rot} \mathbf{v} + \mathbf{u} \times \operatorname{rot} \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{u}$

•  $(\mathbf{u} \cdot \nabla) \mathbf{u} = \operatorname{rot} \mathbf{u} \times \mathbf{u} + \frac{1}{2} \nabla |\mathbf{u}|^2$

Eulerov integrál 2. druhu

**Gamma funkcia**

$$\Gamma(z) = \int_0^{\infty} t^{z-1} e^{-t} dt, \quad \Re(z) > 0$$

$$\Gamma(n) = (n-1)!, \quad n \in \mathcal{N}$$

$$\Gamma(z+1) = z\Gamma(z)$$

$$\Gamma(z)\Gamma(1-z) = \frac{\pi}{\sin \pi z}, \quad 0 < z < 1$$

$$\Gamma\left(-\frac{3}{2}\right) = \frac{4\sqrt{\pi}}{3}$$

$$\Gamma\left(-\frac{1}{2}\right) = -2\sqrt{\pi}$$

$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$$

$$\Gamma\left(\frac{3}{2}\right) = \frac{\sqrt{\pi}}{2}$$

$$\Gamma\left(\frac{5}{2}\right) = \frac{3\sqrt{\pi}}{4}$$

$$\Gamma\left(\frac{7}{2}\right) = \frac{15\sqrt{\pi}}{8}$$

Eulerov integrál 1. druhu

**Beta funkcia**

$$B(z_1, z_2) = \int_0^1 t^{z_1-1} (1-t)^{z_2-1} dt, \quad \Re(z_1), \Re(z_2) > 0$$

$$B(z_1, z_2) = \frac{\Gamma(z_1)\Gamma(z_2)}{\Gamma(z_1+z_2)}$$

$$B(z_1, z_2) = B(z_2, z_1)$$

$$B(z_1, z_2) = B(z_1, z_2+1) + B(z_1+1, z_2)$$

$$B(z_1, z_2) \cdot B(z_1+z_2, 1-z_2) = \frac{\pi}{z_1 \sin(\pi z_2)}$$

$$B(z_1+1, z_2) = B(z_1, z_2) \cdot \frac{z_1}{z_1+z_2}$$

$$B(z_1, z_2+1) = B(z_1, z_2) \cdot \frac{z_2}{z_1+z_2}$$